



# A Matlab Implementation of the Minpack-2 Test Problem Collection

**Dr Shaun Forth**

`S.A.Forth@cranfield.ac.uk`

**AD2016 - 12<sup>th</sup> – 15<sup>th</sup> September 2016**

[www.cranfield.ac.uk](http://www.cranfield.ac.uk)



# Outline

- 1 Introduction
- 2 Matlab Implementation of Minpack-2 Problems
- 3 Example
- 4 Testing
- 5 Interfacing with Optimization Toolboxes
- 6 Results
- 7 Conclusions
- 8 Further Work



# Introduction

1

## Introduction

- AD Packages in Matlab
- The Minpack-2 Test Problem Collection



## Introduction

- **Grad** [Rich and Hill, 1992] - forward mode AD on a Matlab string via Turbo-C
- **ADMAT** [Verma, 1999] - forward and reverse (via tape) mode AD using OO features of Matlab (+ second order derivatives and sparsity detection)
- **ADiMat** [Bischof et al., 2003] - source transformed forward/reverse mode
- **MAD** [Forth, 2006] - optimised derivatives storage class `derivvec` to give improved overloaded forward mode performance over ADMAT
- **MSAD** [Kharche and Forth, 2006] - source-transformation by specialising and inlining MAD's derivative objects.
- **ADiGator** [Patterson et al., 2013, Weinstein and Rao, 2015] - source-transformed, sparsity-exploiting forward mode AD (vertex elimination with forward ordering [Griewank and Reese, 1991]).

Need for testcases.



# The Minpack-2 Test Problem Collection [Averick et al., 1991]

- Describes 24 optimisation problems, including Fortran 77 source code, of three **problem types**:
  - unconstrained minimisation - objective function, gradient, Hessian
  - least squares minimisation - residual, Jacobian
  - systems of nonlinear equations - residual, Jacobian
- For **large-scale problems** source code for Hessian/Jacobian sparsity pattern and Hessian/Jacobian-vector products also provided.
- Appears 82 times in Scopus
- Widely used for AD tool validation, eg, Bischof et al. [1996], Walther and Griewank [2004], Naumann and Utke [2005], Giering and Kaminski [2006], Shin and Hovland [2007], Forth et al. [2004].



# Matlab Implementation of Minpack-2 Problems

- 2 Matlab Implementation of Minpack-2 Problems
  - Converting Minpack-2 to Matlab
  - Re-coding Minpack-2 in Matlab



## Converting Minpack-2 to Matlab

- Lenton [2005] hand-converted all the Minpack problems to Matlab
  - ▶ Changes of syntax, array constructors
  - ▶ Arrays must have lower index 1 in Matlab (also affects loop indices)
- Validated by
  - ▶ Fortran program creates random vectors  $\mathbf{x}$ , calls Fortran Minpack, writes  $f(\mathbf{x})$ ,  $\nabla f$ , ... to formatted text file.
  - ▶ Text file read into Matlab and results compared to those from Matlab version of Minpack calls
  - ▶ Results agree to within i/o and floating point round-off



## Re-coding Minpack-2 in Matlab

- Lenton's conversion satisfactory for small-scale, fixed  $n$  problems.
- For large scale problems Lenton's Fortran-based coding uses loops and subscripting operations.
- Large number of overloaded function calls in overloaded AD.
- Re-coded Minpack-2 problems using array operations to give a **vectorised version**.
- **Uniform interface** to all functions with problem specific parameters supplied in a structure.





## Re-coding Minpack-2 in Matlab (ctd.)

- **Separate functions** for:
  - ▶ Setting problem parameters - constants, standard start vector, etc
  - ▶ Function evaluation only + vectorised version where appropriate.
  - ▶ Function + Gradient/Jacobian
  - ▶ Gradient/Jacobian only
  - ▶ Jacobian/Hessian-vector product
  - ▶ Sparsity pattern.
- Use Matlab's **Code Analyzer** to eliminate: dead code, unused variables.
- Hand-coded adjoint for gradients.



## Example

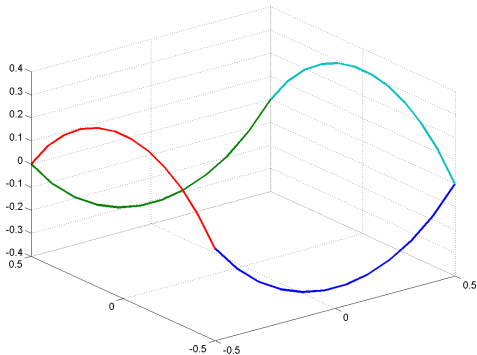
### 3 Example

- Minimal Surface Area (MSA) Problem



## Minimal Surface Area (MSA) Problem

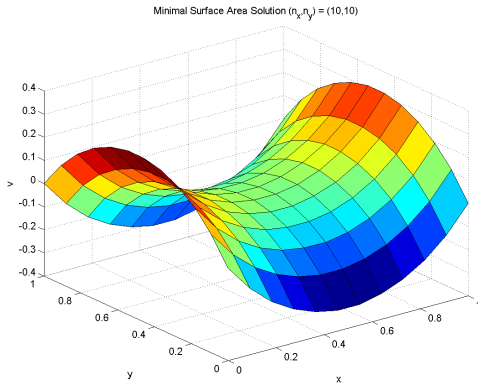
- Supply height on  $x$  and  $y$  boundaries of  $[-\frac{1}{2}, \frac{1}{2}] \times [-\frac{1}{2}, \frac{1}{2}]$





# Minimal Surface Area (MSA) Problem

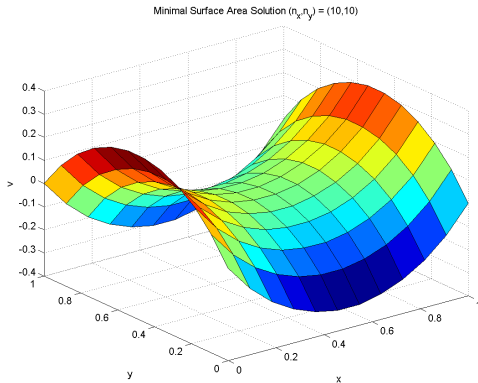
- Supply height on  $x$  and  $y$  boundaries of  $[-\frac{1}{2}, \frac{1}{2}] \times [-\frac{1}{2}, \frac{1}{2}]$
- Determine surface  $u(x, y)$  of minimal surface area with given boundaries.





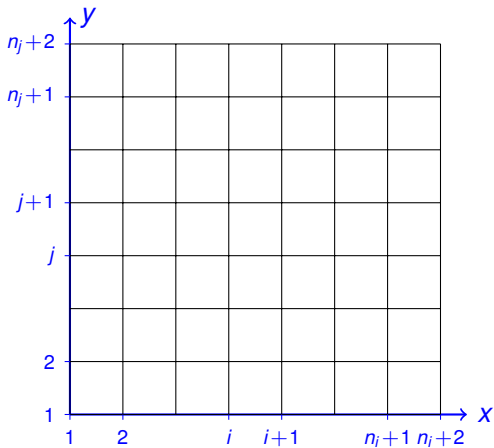
## Minimal Surface Area (MSA) Problem

- Supply height on  $x$  and  $y$  boundaries of  $[-\frac{1}{2}, \frac{1}{2}] \times [-\frac{1}{2}, \frac{1}{2}]$
- Determine surface  $u(x, y)$  of minimal surface area with given boundaries.
- Known analytic solution due to Enneper.



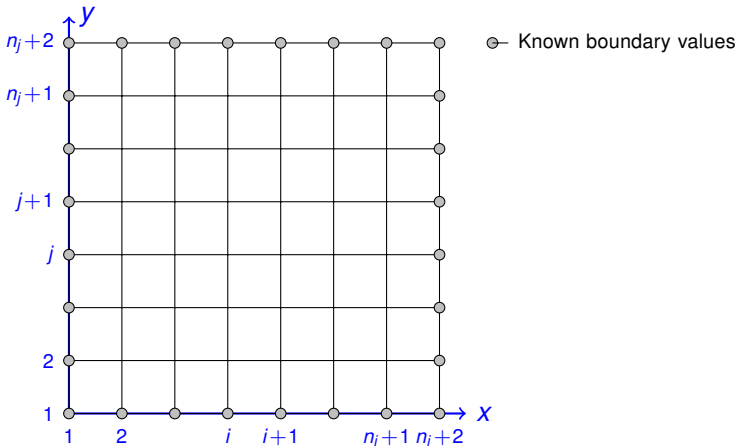


# MSA - Finite Difference Formulation



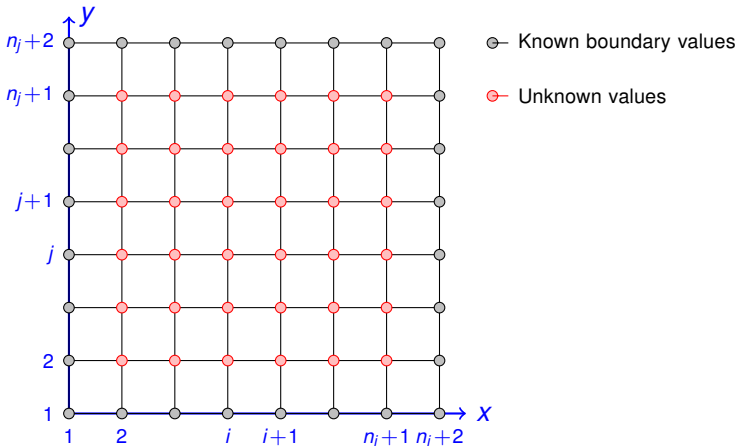


# MSA - Finite Difference Formulation





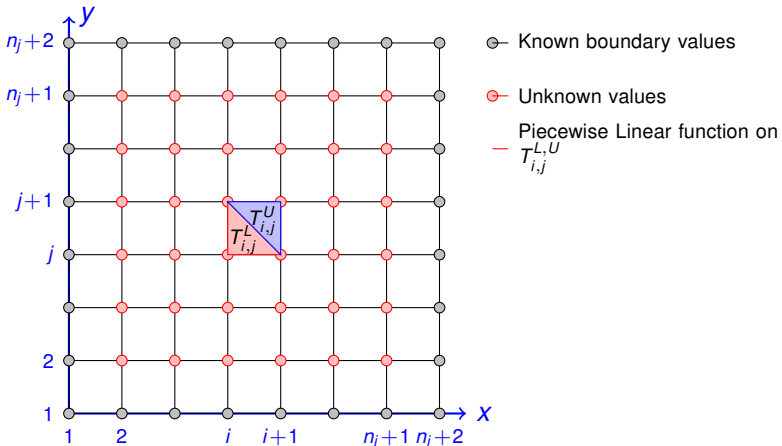
# MSA - Finite Difference Formulation



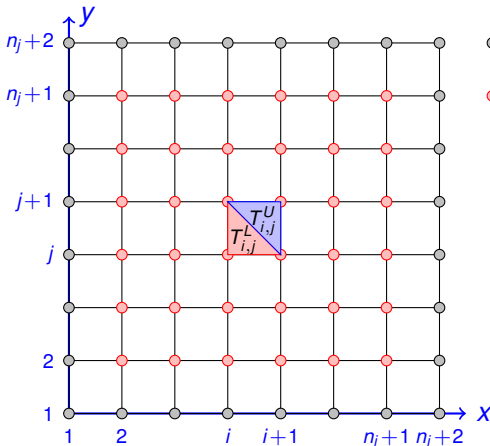




# MSA - Finite Difference Formulation



# MSA - Finite Difference Formulation



○ Known boundary values

○ Unknown values

Piecewise Linear function on

—  $T_{i,j}^{L,U}$

Min  $f(u)$  =

—  $\sum_{i=1}^{n_i+1} \sum_{j=1}^{n_j+1} (f_{i,j}^L + f_{i,j}^U)$



## MSA - Finite Difference Formulation (ctd.)

Minimise,

$$f(u) = \sum_{i=1}^{n_i+1} \sum_{j=1}^{n_j+1} (f_{i,j}^L + f_{i,j}^U),$$

with  $f_{i,j}^{L,U}$  the surface area on the lower/upper triangles:

$$f_{i,j}^L = \frac{h_x h_y}{2} \left\{ 1 + \left( \frac{u_{i+1,j} - u_{i,j}}{h_x} \right)^2 + \left( \frac{u_{i,j+1} - u_{i,j}}{h_y} \right)^2 \right\}^{\frac{1}{2}}$$

$$f_{i,j}^U = \frac{h_x h_y}{2} \left\{ 1 + \left( \frac{u_{i+1,j+1} - u_{i,j+1}}{h_x} \right)^2 + \left( \frac{u_{i+1,j+1} - u_{i+1,j}}{h_y} \right)^2 \right\}^{\frac{1}{2}}$$

and we only consider  $u_{i,j}$  with  $i = 2, \dots, n_i + 1, j = 2, \dots, n_j + 1$ .

## MSA - Fortran Coding (much abbreviated)

```
subroutine dmsafg(nx,ny,x,f,fgrad,task,bottom,top,left,right)
```

```
:
```

```
c function and gradient over the lower triangular elements.
```

```
do 50 j = 0, ny
```

```
do 40 i = 0, nx
```

```
    k = nx*(j-1) + i ! 1-D indexing
```

```
    if (i .ge. 1 .and. j .ge. 1) then
```

```
        v = x(k) ! first vertex in triangle
```

```
    else
```

```
        if (j .eq. 0) v = bottom(i+1)
```

```
:
```

```
    if (i .lt. nx .and. j .gt. 0) then
```

```
        vr = x(k+1) ! right vertex
```

```
:
```

```
        dvdx = (vr-v)/hx
```

```
        dvdy = (vt-v)/hy
```

```
        fl = sqrt(one+dvdx**2+dvdy**2)
```

```
        if (feval) f = f + fl
```

```
    if (geval) then
```

## MSA - Lenton's Matlab Conversion

```
function varargout=dmsafg(nx,ny,x,task,bottom,top,left,right)
:
switch task
    case {'F','G','FG'}
        for j = 0:ny
            for i = 0:nx
                k = nx*(j-1) + i; % 1-D indexing
                if i >= 1 && j >= 1
                    v = x(k); % first vertex in triangle
                else if j == 0
                    v = bottom(i+1);
                :
                if i < nx && j > 0
                    vr = x(k+1); % right vertex
                :
                dvdx = (vr-v)/hx;
                dvdy = (vt-v)/hy;
                fl = sqrt(1+dvdxdx^2+dvdxdy^2);
                if geval
```

## MSA - Re-Coding the Problem Definition

Structure `Prob` used to store all problem data

```
function [Prob,nuse]=MinpackMSA_Prob(varargin)
%   [Prob,nuse]=MinpackMSA_Prob(nx,ny,bottom,top,left,right,compat)
% check/set boundary conditions
if isempty(bottom)
    bottom=Enneper('bottom',nx,ny);
elseif ~(isvector(bottom)&&length(bottom)==nx+2)
    error(['MinPackMSA_Prob: bottom must be a length nx+2 = ',...
end
:
% Compute the standard starting point
x_0 = reshape((top(2:nx+1)*alpha + bottom(2:nx+1)*(1-alpha) +...
Prob.x_0=x_0;
Prob.user.nx=nx;
:
nuse=nx*ny;

function bcvec=Enneper(bc,nx,ny)
```



## MSA - Re-Coding the Function Definition

Regularise the interface to use `Prob` structure

```
function f = MinpackMSA_F(x,Prob)
:
bottom=Prob.user.bottom;
top    =Prob.user.top;
left   =Prob.user.left;
right  =Prob.user.right;
```

otherwise similar to Lenton coding with loops and branching.

## MSA - Vectorising the Function Definition

```
function f = MinpackMSA_Fvec(x,Prob)
:
bottom=Prob.user.bottom;
:
% transfer interior values x to entire grid v
v = zeros(nx+2,ny+2,'like',x); % 'like' ensures v has class of x
v(2:nx+1,2:ny+1) = reshape(x,nx,ny);
% apply boundary conditions
v(:,1) = bottom;
:
% computer dvdx and dvdy on each edge of the grid
dvdx = (v(2:nx+2,:)-v(1:nx+1,:))/hx;
dvdy = (v(:,2:ny+2)-v(:,1:ny+1))/hy;
% quadratic term over lower and upper elements
fL=sqrt(1+dvdx(1:nx+1,1:ny+1).^2+dvdy(1:nx+1,1:ny+1).^2);
fU=sqrt(1+dvdx(1:nx+1,2:ny+2).^2+dvdy(2:nx+2,1:ny+1).^2);
f = area*(sum(sum(fL+fU)));
```

**No loops or branches!**



## MSA - Vectorised Gradient

From vectorised function - easy (!) to write vectorised gradient

```
function fgrad = MinpackMSA_Gvec(x,Prob)
% coding as for MinpackMSA_Fvec
:
% quadratic term over lower and upper elements
fL=sqrt(1+dvdxdx(1:nx+1,1:ny+1).^2+dvdxdy(1:nx+1,1:ny+1).^2);
fU=sqrt(1+dvdxdx(1:nx+1,2:ny+2).^2+dvdxdy(2:nx+2,1:ny+1).^2);
% gradient just use interior points
i=2:nx+1;
j=2:ny+1;
fgrad=area*(...
    (1/hx)*(1./fL(i-1,j)+1./fU(i-1,j-1)).*dvdxdx(i-1,j)...
    -(1/hx)*(1./fL(i,j)+1./fU(i,j-1)).*dvdxdx(i,j)...
    +(1/hy)*(1./fL(i,j-1)+1./fU(i-1,j-1)).*dvdxdy(i,j-1)...
    -(1/hy)*(1./fL(i,j)+1./fU(i-1,j)).*dvdxdy(i,j));
fgrad=fgrad(:);
```



# Testing

## 4 Testing



## Testing

- Unit testing describe at Euro AD Workshop in Paderborn
- Validate Matlab coding against original Fortran coding.



# Interfacing with Optimization Toolboxes

## 5 Interfacing with Optimization Toolboxes

- Interfacing with TOMLAB
- Interfacing with Matlab Optimization Toolbox



# Interfacing with TOMLAB

## [Kenneth Holmström et al., 2010]

- Set up the Minpack problem

```
n = 100;  
Prob = MinpackMSA_Prob(n, 'Tomlab');
```

- Using the Minpack Function and Gradient

```
Result = ucSolve(Prob);
```

- Or, using the Minpack Function and MAD Gradient

```
Prob.FUNCS.g=[];  
options = struct; options.derivatives = 'automatic';  
Result = ucSolve(Prob,options);
```

- Obtain the optimal value

```
x = Result.x_k;  
f = Result.f_k;
```



# Interfacing with Matlab Optimization Toolbox [Mathworks, 2016]

- Set up the Minpack problem

```
n = 100;  
Prob = MinpackMSA_Prob(n, 'Tomlab');
```

- Using the Minpack Function and Gradient

```
options = optimoptions('fminunc', 'Algorithm', ...  
    'quasi-Newton', 'SpecifyObjectiveGradient', true);  
[x,f]=fminunc(@(x)MinpackMSA_FG(x,Prob),Prob.x_0,options);
```

- Or, using the Minpack Function and MAD Gradient [Forth and Ketzscher, 2004]

```
options=optimset(@fminunc);  
options = optimsetMAD(options, 'GradObj', 'fmadsparse');  
[x,f]=fminuncMAD(@(x)MinpackMSA_F(x,Prob), ...  
    Prob.x_0,options);
```



# Results

6

## Results

- MSA Problem
- MSA - Minimization Performance



## Results

- Processor - Intel Core i5-4300U CPU (1.9-2.5GHz) with 4 GB RAM
- OS - Windows 7
- Matlab - release 2016a
- Multi-threading not exploited.





## MSA Problem - Run time Ratios

what	how	vectorized	Problem size		
			100	400	1600
F	Minpack	no	1	1	1
F	Minpack	yes	1.00	0.75	0.38
F+G	Minpack	no	3.00	2.00	1.75
F+G	Minpack	yes	4.00	1.50	0.81
F+G	<i>fmad-sparse</i>	no	16000.00	24250.00	23125.00
F+G	<i>fmad-sparse</i>	yes	220.00	145.00	106.25

- Function CPU times =  $0.078ms$ ,  $0.078ms$  and  $0.25ms$
- Minpack timings averaged over 1000 evaluations, *fmad* over 1 and *fmad-sparse* over 50.



## MSA - Minimization Performance

Chose solvers with BFGS updates to inverse Hessian:

- Tomlab `ucSolve` [Kenneth Holmström et al., 2010]
- Matlab Optimization Toolbox `fminunc` [Mathworks, 2016]
- MAD interface `fminuncMAD` to `fminunc` [Forth and Ketzscher, 2004]

All use Minpack standard start point, default tolerances and converge to same solution.



# MSA - Minimization Performance

## Run Times (s)

solver	gradient	vectorized	Problem size		
			100	400	1600
ucSolve	Minpack	no	0.50	0.91	41.31
ucSolve	Minpack	yes	0.16	0.87	38.78
ucSolve	FD	no	0.41	3.49	49.64
ucSolve	FD	yes	0.62	2.98	31.48
ucSolve	fmad-sparse	no	0.36	3.34	51.03
ucSolve	fmad-sparse	yes	0.44	3.01	31.25
fminunc	Minpack	no	0.07	0.28	6.93
fminunc	Minpack	yes	0.05	0.23	6.77
fminunc	FD	no	0.20	2.26	54.52
fminunc	FD	yes	0.25	1.86	29.00
fminuncMAD	fmad-sparse	no	182.71	-	-
fminuncMAD	fmad-sparse	yes	3.70	19.53	329.41



# Conclusions

## 7 Conclusions



## Conclusions

- We have a validated (well nearly) Matlab implementation of all problems in the Minpack-2 Test Problem Collection.
- Re-coded version with uniform interface and an implementation of the function alone to allow testing of AD for
  - ▶ First Derivatives for Jacobians and gradients
  - ▶ Sparsity Patterns for Jacobians and Hessians
  - ▶ Jacobian-vector and Hessian-vector products
  - ▶ Impact of code vectorisation.
- Code vectorisation will have a major impact on efficiency of overloaded and source transformed AD codes - including **compile-time** costs for source transformation.
- Code vectorisation almost always beneficial to performance and crucial for overloaded AD.



# Further Work

## 8 Further Work



## Further Work

- Package up our Matlab version of the Minpack-2 problems for users in AD and Optimization.
- Present `fmad` class uses obsolete Matlab OO coding practices - recoding should allow JIT acceleration to be applied.
- Reverse mode AD in MAD?



## References I

- B. M. Averick, R. G. Carter, and J. J. More. The Minpack-2 Test Problem Collection. Technical Memorandum TM 150, Argonne National Laboratory, Mathematics and Computer Science Division, 9700 South Cass Avenue, Argonne, Illinois 60439, USA, May 1991. URL <ftp://ftp.mcs.anl.gov/pub/MINPACK-2/tprobs.92/P153.ps.Z>.
- C. Bischof, P. Khademi, A. Bouaricha, and A. Carle. Efficient computation of gradients and jacobians by dynamic exploitation of sparsity in automatic differentiation. *Optimization Methods and Software*, 7(1):1–39, 1996. ISSN 1055-6788.
- C. Bischof, B. Lang, and A. Vehreschild. Automatic Differentiation for MATLAB Programs. *Proceedings in Applied Mathematics and Mechanics*, 2(1):50–53, Mar. 2003. ISSN 1617-7061. doi: 10.1002/pamm.200310013. URL <http://onlinelibrary.wiley.com/doi/10.1002/pamm.200310013/abstract>.
- S. Forth, M. Tadjouddine, J. Pryce, and J. Reid. Jacobian code generated by source transformation and vertex elimination can be as efficient as hand-coding. *ACM Transactions on Mathematical Software*, 30(3):266–299, 2004. ISSN 0098-3500. doi: 10.1145/1024074.1024076.
- S. A. Forth. An efficient overloaded implementation of forward mode automatic differentiation in MATLAB. *ACM Trans. Math. Softw.*, 32(2):195–222, June 2006. ISSN 0098-3500. doi: 10.1145/1141885.1141888. URL <http://doi.acm.org/10.1145/1141885.1141888>.





## References II

- S. A. Forth and R. Ketzschner. High-Level Interfaces for the MAD (Matlab Automatic Differentiation) Package. In P. Neittaanmaki, T. Rossi, S. Korotov, E. Onate, and J. Periaux, editors, *4th European Congress on Computational Methods in Applied Sciences & Engineering (ECCOMAS)*, Jyvaskyla, Finland, July 2004. URL <http://www.mit.jyu.fi/eccomas2004/proceedings/pdf/641.pdf>.
- R. Giering and T. Kaminski. *Automatic Sparsity Detection implemented as a source-to-source transformation*, volume 3994 LNCS - IV of *Lecture Notes in Computer Science (including subseries Lecture Notes in Artificial Intelligence and Lecture Notes in Bioinformatics)*. 2006. ISBN 3540343857.
- A. Griewank and S. Reese. On the Calculation of Jacobian Matrices by the Markowitz Rule. In A. Griewank and G. F. Corliss, editors, *Automatic Differentiation of Algorithms - Theory, Implementation, and Application*, pages 126–135. SIAM, Philadelphia, PA, 1991. ISBN 0-89871-284-X.
- Kenneth Holmström, Anders O. Göran, and Marcus M. Edvall. Users Guide for TOMLAB 7. Technical report, TOMLAB Optimization, May 2010. URL <http://tomopt.com/docs/TOMLAB.pdf>.
- R. Kharche and S. Forth. Source transformation for MATLAB automatic differentiation. In V. Alexandrov, G. van Albada, P. Sloot, and J. Dongarra, editors, *Computational Science – ICCS 2006*, volume 4 of *Lecture Notes in Computer Science*, pages 558–565. 2006. ISBN 978-3-540-34385-1. URL [http://link.springer.com/chapter/10.1007%2F11758549\\_77](http://link.springer.com/chapter/10.1007%2F11758549_77).



## References III

- K. Lenton. *An Efficient, Validated Implementation of the MINPACK-2 Test Problem Collection in MATLAB*. MSc Dissertation, Cranfield University, Applied Mathematics & Operational Research Group, Engineering Systems Department, RMCS Shrivenham, Swindon SN6 8LA, UK, 2005.
- Mathworks. Optimization Toolbox - User's Guide. Technical Report R2016a, The MathWorks, Inc. 3 Apple Hill Drive Natick, MA 01760-2098, 2016. URL [http://www.mathworks.com/help/pdf\\_doc/optim/optim\\_tb.pdf](http://www.mathworks.com/help/pdf_doc/optim/optim_tb.pdf).
- U. Naumann and J. Utke. Optimality-preserving elimination of linearities in Jacobian accumulation. *Electronic Transactions on Numerical Analysis*, 21:134–150, 2005. ISSN 1068-9613.
- M. A. Patterson, M. Weinstein, and A. V. Rao. An efficient overloaded method for computing derivatives of mathematical functions in MATLAB. *ACM Trans. Math. Softw.*, 39(3):17:1–17:36, May 2013. ISSN 0098-3500. doi: 10.1145/2450153.2450155. URL <http://doi.acm.org/10.1145/2450153.2450155>.
- L. Rich and D. Hill. Automatic differentiation in MATLAB. *Applied Numerical Mathematics*, 9(1):33–43, 1992. ISSN 0168-9274. doi: 10.1016/0168-9274(92)90065-L.
- J. Shin and P. Hovland. Comparison of two activity analyses for automatic differentiation: Context-sensitive flow-insensitive vs. context-insensitive flow-sensitive. *Proceedings of the ACM Symposium on Applied Computing*, pages 1323–1329, 2007. doi: 10.1145/1244002.1244287.



## References IV

- A. Verma. ADMAT: Automatic Differentiation in MATLAB Using Object Oriented Methods. In M. E. Henderson, C. R. Anderson, and S. L. Lyons, editors, *Object Oriented Methods for Interoperable Scientific and Engineering Computing: Proceedings of the 1998 SIAM Workshop*, pages 174–183. SIAM, Philadelphia, 1999.
- A. Walther and A. Griewank. ADOL-C: Computing higher-order derivatives and sparsity pattern for functions written in C/C++. 2004.
- M. J. Weinstein and A. V. Rao. ADiGator, a Toolbox for the Algorithmic Differentiation of Mathematical Functions in MATLAB Using Source Transformation via Operator Overloading. *ACM Transactions on Mathematical Software*, Submitted, 2015. URL <http://vdol.mae.ufl.edu/SubmittedJournalPublications/adigator-CALGO.pdf>.



**[www.cranfield.ac.uk](http://www.cranfield.ac.uk)**

**T: +44 (0)1793 785810**

 @cranfielduni

 @cranfielduni

 /cranfielduni